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**103.13330.2012**

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**2.06.14-85**

27 2002 . 184- « 19 », 2008 . 858 « - ».

1 « » - « »

2 465 « »

3 ,

4 ) 30 2012 . 269 1 2013 .

5 ( ). 103.13330.2011 « 2.06.14-85 »

( ) « », « » - « ».

’ - ( )

1	.....	1
2	.....	1
3	.....	2
4	.....	3
5	.....	9
6	.....	16
7	.....	22
8	, .....	32
9	.....	34
( )	( ) .....	38
( )	.....	55
( )	.....	63
	.....	67



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**Protection of mines against ground or surface water**


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2013-01-01

**1**

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**2**

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 2.1.5.1059-01 «  
 »  
 23.13330.2011 « 2.02.02-85\* »  
 32.13330.2012 « 2.04.03-85 « .  
 »  
 39.13330.2012 « 2.06.05-84\* »  
 45.13330.2012 « 3.02.01-87 ,  
 »  
 47.13330.2012 « 11-02-96 .  
 »  
 69.13330.2012 « 3.02.03-84 »  
 91.13330.2012 « II-94-80 »  
 104.13330.2012 « 2.06.15-85  
 »  
 116.13330.2012 « 22-02-2003 ,  
 »  
 2.1.5.980-00  
 2.1.5.2582-10 -  
 2.1.5.2582-10 « -

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- 1
- 3
- 3.1 (pumping, water-removing):
- 3.2 (water depression, sink of subterranean water):
- 3.3 (aquiclude):
- 3.4 ( ) (depression curve):
- 3.5 ( ) (mould, subsidence trough):
- 3.6 (range, zone of injection):
- 3.7 (wellpoint):
- 3.8 (full gallop, opencast mine):
- 3.9 (piezometric surface):
- 3.10 (piezometric level):
- 3.11 (imbibition water, pit water):
- 3.12 ( ) (cased hole with filters):

( ),

3.13 (plugging, refilling):

3.14 (cementation, grouting):

3.15 (mine):

3.16 (mine gallery):

#### 4

4.1

4.2

116.13330, 104.13330.

[2], [3]

4.3

4.4

47.13330

4.5





4.9

, ( );  
 , ( );  
 , . . ) ( , );  
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 4.10 , ,  
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4.11

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 ( .4.10),  
 ( 7)

4.12

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4.13

( , 4.14 , ).

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( . 4.10-4.13);

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4.15

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4.16

4.10–4.13.

4.17

4.18

4.15,

4.19

( .4.16–4.18);

5

5.1

5.2

5.3

4.9.

5.4

0,001 / ),

5.3.

$$y \leq 5h_d, \tag{1}$$

$h_d -$

(1)

( ) ,

4.15.

5.5

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5.6

5.7

,

$$v = kI, \tag{2}$$

$v$  –

$k$  –

$I$  –

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5.8

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5.9

5.10

( , , )

(  $2 /$  )

5.11

5.12

5.13 ( ) ,

5.14 ,

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5.15 ,

( , ),

( 5.16 , ).

5.17 ( , )

5.18 ( ), ( ) -

5.19

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5.20

5.21

5.22

12-15

5.23

)

-

4-5

-

5-50 / -  
2-5 / -

5.24

0,5-2  
0,5-5

45.13330.

5.25

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5.26

5.27

- 20 ),

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103.13330.2012

5.38

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5.39

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5.40

5.41

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5.42

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5.43

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8.

5.44

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91.13330.

5.45

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5.46

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5.47

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6.1

6.2

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8,

6.3

100

6.4

6.5

6.6

6.7 1,5 3 / .  
 ( , , , . ).  
 - (9.2).

6.8

6.9 8.  
 ( )

6.10 ( , , )

6.11 ( ).

( )

6.12 - , , ,  
 ( . , 8)

3-

5-

6.13  
 ( )

6.10-6.12

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( )  
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6.14

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	5	5-10	10-20	. 20
2	30	25	20	15
2-10	60	40	30	25
10-20	100	70	50	40
20	120	90	60	50

6.15

，  
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6.16 ( ). ( . 6.12),

6.17 [18]. ( )

6.18

9.

25 %

6.19

32.13330

6.20

6.21

6.22

[19] [20].

6.23

( . 6.18).

)  
200 ,  
(  
)-

200 .

80  
6.24

1000 <sup>3/</sup> .

6.25

6.26

0,5

6.27

10

6.28

6.29

6.30

6.22 91.13330.

( 5 . 3/ )

6.31

(1 / 2).

6.32

( < 5)

6.33

6.34

6.35

( )

)

(



6.36		200	
			20
6.37			
6.38			
6.39			
6.40			( 250 ) -
6.41			
6.42			
6.43		69.13330.	
6.44	91.13330.	8 3/	
6.45			
	600		
6.46			
6.47	( . 6.22)		91.13330.

6.48 , , , , [18], [19], [20], [21] [22].

6.49 , . , , ( ), , , , ( , ), .

6.50 . 6.51 , , [18], [19], [20] [21] [22], 10 . 6.52

-I ; :  
50<sup>3/</sup> - II ;  
, 50<sup>3/</sup> - III ;  
- II ;  
- I ;  
- III .

7

7.1 ( ): , ,

39.13330.

7.2 23.13330, 45.13330, 69.13330 [16].

7.3

1

7.4

( )

7.5

$H_s$ ,

$$H_s = t_s I_{cr}, \quad (3)$$

$t_s -$   
 $I_{cr} -$

( .4.6).

7.6

( ) ( . 4.14, 7.25).



7.12

7.13

7.14

7.15

7.16

,  
 .  
 (5-20 ),  
 ( )  
 ,  
 20 .  
 45.13330.  
 0,2,  
 0,005 - 30 % 0,05 -  
 10 % 1,10-1,30 / <sup>3</sup>.  
 1,03-1,15 / <sup>3</sup>,  
 45.13330.  
 :  
 - 16-20 ( );  
 15; W2;  
 F50;  
 - 1,5 (15 / <sup>2</sup>); 1,5-1,8 / <sup>3</sup>;  
 98 %; 0,5 / <sup>3</sup>; - ;  
 - ( 10 1/3  
 );  
 ( ,  
 ) - ( )  
 - 10-15 %;  
 ;  
 ,  
 ,

0,005 / .

2.

2

:	100 150
:	20 30 30

7.17 , (10-30 ),  
 ( Jet-grouting),  
 , , , 20  
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 ( )  
 ( ) 70 .  
 ( 5-30 / . )  
 ( )  
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 ( ), (Jet-1,  
 Jet-2, Jet-3 ),  
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 ( , , )

.) ,

7.18 ,

50 ,

7.19 7.23.

0,7-0,75

0,85

7.20 (

7.17),

10-30 /

2 ( . 7.17),

7.21 ,

7.22 ,

7.23

7.24 , , , , , ( ),

103.13330.2012

( )  
45.13330.  
7.25 ( )  
(7.6) ,  
.  
7.26 , ,  
7.27 , ,  
( )  
7.28 ( , , ).  
( , -  
0,1 , 0,01 / / <sup>2</sup>;  
2400 / .  
23.13330 [16].  
, -  
80 / . ( ( , , ),  
( , , ),  
7.27, 7.37.  
1 80 /  
( )  
( « » )  
, , 0,3 0,8 .  
0,1 80 /  
(



),  
 , 0,15–0,4 . , ,  
 ( ), 0,6 ( ( ) )  
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 ), ( ,  
 7.29 , ( ,  
 ( ), , « » , -  
 , , ,  
 7.30 .  
 400 .  
 , ,  
 ( ) « »  
 7.31 , 7.28. ( ) -  
 , -  
 7.32 ( )  
 7.33 ( - 0,2–50 / )  
 2–80 /  
 : ( , 0,5–2,0 / ).  
 - -  
 ( )  
 , , 0,3 1 .

103.13330.2012

7.34

7.35

$I_{cr}$

23.13330

7.36

23.13330

$r_{in}$ ,

$$r_{in} = \sqrt{\frac{q_{in} t}{\pi h_{in} \alpha_e e}}, \quad (4)$$

$q_{in}$  –

$t$  –

$h_{in}$  –

$e$  –

–

(4),

7.37

$1,73r_{in}$ ,

$r_{in} (4)$  ,  
 $1,5r_{in}$ .

)  
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 7.6.  
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 7.38 ( ) .  
 7.39 ( )  
 7.40 .  
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 42-91 ,  
 -91-110 .  
 7.41 ( )  
 12-15 .  
 7.42 ( ),  
 ,  
 .  
 ( .7.37).  
 7.43 ,  
 ,  
 ,  
 ( ) ,  
 ( ) ,  
 ,  
 ( .7.6).

( ) ,

23.13330 [16]

,  
.

( )

7.44

, ( , )

7.45

7.46

( ) ,

3 .

7.47

7.48

: - 30-40 %

- 1-1,5 ,

2-3 .

7.49

7.50

7.51

45.13330, 69.13330 [17].

**8**

8.1

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( ) , ; ,

- ; ( )

8.2 , . ,

( ) , , ,

8.3 , - ,

8.4 , .

8.5 .

5 , ( )-10 .

5 %.

5 : , -5 , ( )-10 .

( )

8.6

5 %.

5 %.

( , . ).

8.7

( . 6).

( )

8.8

8.9

:

0,005,

— 0,05–0,02;

;

[14]

8.10

9.

**9**

9.1

:

9.2 ;  
8 «  
»,

4.14 4.19.

9.3 : [2], [3], [10], [11]

32.13330.

[8], 2.1.5.980

2.1.5.1059.

[9], 2.1.5.2582.

[12]  
).

9.4 [4].

9.3,

9.5

9.3, 32.13330 [15].

9.6

( )  
2.1.5.980.

9.7

[2], [3]

9.8

( ),







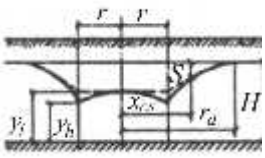
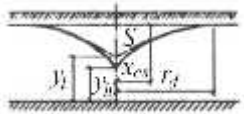
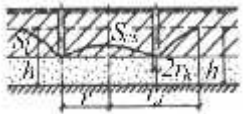
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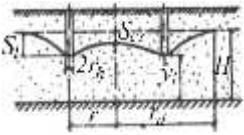
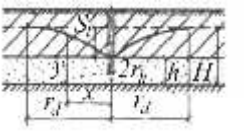
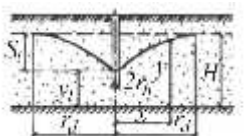
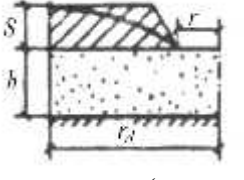
(.1)

.1

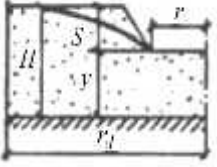
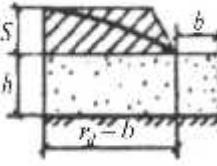
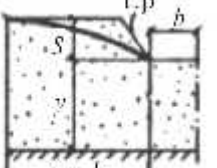
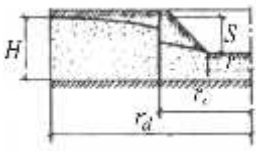
.1

<p>1</p> 	$\Phi = \frac{\ln \frac{r_d}{x_{cs}}}{2\pi}$ $\Phi = \frac{r \ln \frac{r_d}{x_{cs}}}{2\pi l_c}$ <p style="text-align: center;"><math>x_s = r</math></p>
<p>2</p> 	$\Phi = \frac{r_d - x_{cs}}{l}$
<p>3</p>  <p><math>S_l</math></p>	$\Phi = \frac{\ln \frac{r_d}{r+h} + \frac{h}{\pi r} \ln \frac{8r}{r_h}}{2\pi}$ $\Phi = \frac{\left( \ln \frac{r_d}{r+h} + \frac{h}{\pi r} \ln \frac{8r}{r_h} \right) r}{l_c}$

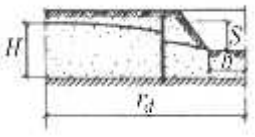
.1

<p>4</p>  <p><math>S_l</math></p>	$\Phi = \frac{\ln \frac{r_d}{r+y_l} + \frac{y_l}{\pi r} \ln \frac{8r}{r_h}}{2\pi}$ $\Phi = \frac{(\ln \frac{r_d}{r+y_l} + \frac{y_l}{\pi r} \ln \frac{8r}{r_h})r}{l_c}$
<p>5</p>  <p><math>S_l</math></p>	$\Phi = \left( \frac{2h}{\pi} \ln \frac{h}{\pi r_h} + r_d \right) \frac{1}{l}$
<p>6</p>  <p><math>S_l</math></p>	$\Phi = \frac{2h}{l \left( \frac{S}{r_d} + \frac{1}{\frac{r_d}{2y_l} + \frac{1}{\pi} \ln \frac{y_l}{\pi r_h}} \right)}$
<p>7</p>  <p>( )</p>	$\frac{r}{h} \geq 0,5 \quad \Phi = \frac{\ln \frac{r_d}{r} + \frac{0,44h}{r}}{2\pi};$ $\frac{r}{h} \leq 0,5 \quad \Phi = \frac{\left( \frac{\pi}{2} + 2 \arcsin \frac{r}{h + \sqrt{h^2 + r^2}} + 0,515 \frac{r}{h} \ln \frac{r_d}{4h} \right) h}{2\pi r}$

.1

<p>8</p>  <p>( )</p>	$\frac{r}{y} \geq 0,5 \quad \Phi = \frac{h}{\pi \left( \frac{S}{\ln \frac{r_d}{r}} + \frac{0,44y}{r} + \ln \frac{r_d}{r} \right)};$ $\frac{r}{y} \leq 0,5 \quad \Phi = \frac{h}{\pi \left( \frac{S}{\ln \frac{r_d}{r}} + \frac{2r}{\frac{\pi}{2} + 2 \arcsin \frac{r}{y + \sqrt{y^2 + r^2}}} + 0,515 \frac{r}{y} \ln \frac{r_d}{4y} \right)}$
<p>9</p>  <p>( )</p>	$\frac{b}{h} \geq 0,5 \quad \Phi = \frac{r_d - b + 0,44h}{l};$ $\frac{b}{h} < 0,5 \quad \Phi = \frac{r_d - b + 0,638h \ln \frac{4h}{\pi b}}{l}$
<p>10</p>  <p>( )</p>	$\frac{b}{y} \geq 0,5 \quad \Phi = \left[ \frac{S}{2(r_d - b) - \frac{\beta^2 S^2}{2(r_d - b)}} + \frac{y}{r_d - b + 0,44y} \right] l;$ $\frac{b}{y} < 0,5 \quad \Phi = \left[ \frac{S}{2(r_d - b) - \frac{\beta^2 S^2}{2(r_d - b)}} + \frac{y}{r_d - b + 0,638y \ln \frac{4y}{\pi b}} \right] l$
<p>11</p> 	$\Phi = \frac{\ln \frac{r_d}{r} + \frac{kt_s}{k_s r_s}}{2\pi}$

.1

<p>12</p> 	$\Phi = \frac{r_d - b + t_s \left( \frac{k}{k_s} - 1 \right)}{l}$
---	---

.7

( )

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( )

$$r(r_s) = \sqrt{\frac{A}{\pi}} \quad (.2)$$

10 ( )  
(  $l < 2L$  )

$$r = 0,25l; \quad (.3)$$

(  $l \geq 2L$  ) ( )

$$r = 0. \quad (.4)$$

.8

$r_d$

— — — .2 ,

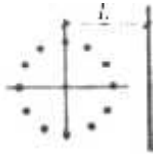
$$r_d = L. \quad (.5)$$

.9

( )

( )

.2

<p>1</p> 	<p>,</p>	$r_d = 2L$
--	----------	------------

.2

	<p>— b—</p>	<p>, <math>r_d = \frac{2L_1L_2}{\sqrt{L_1^2 + L_2^2}};</math>  <math>a, b \quad r_d = 2L_1\sqrt{\frac{L_1^2}{L_2^2} + 1}</math></p>
	<p>— b—</p>	<p>, <math>r_d = \frac{2}{\pi} L_1 \sin \frac{\pi L_2}{L_1};</math>  <math>a, b \quad r_d = \frac{4}{\pi} L_1 \text{ctg} \frac{\pi L_2}{2L_1}</math></p>
	<p>P</p>	<p>, <math>r_d = r + H\sqrt{\frac{k}{2P}}</math></p>
	<p>,</p>	<p>, <math>r_d = r + \sqrt{\frac{kh_1h}{k_d}}</math></p>

.10

)

1 .3

( .1),

$r_d,$

$$r_d = r + 1,5\sqrt{at} . \quad ( .6)$$

$$a_{lc} = \frac{kh}{\mu_g}; \quad a_{pc} = \frac{kh}{\mu_e} . \quad ( .7)$$

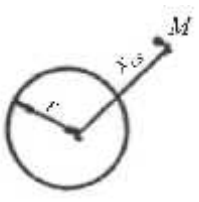
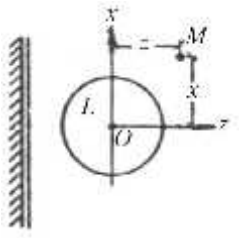
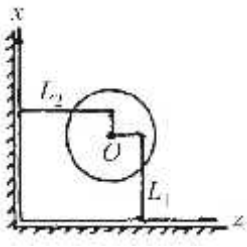
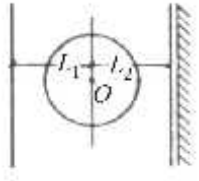
2-7

.3.

.3

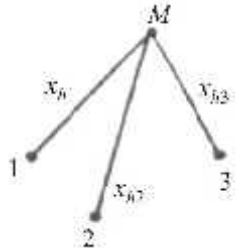
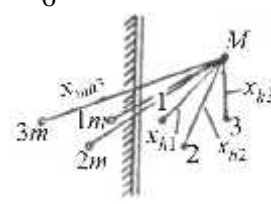
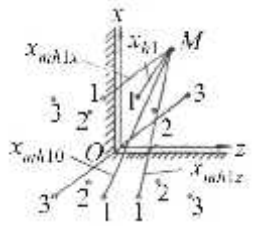
i (-u)

.4.

<p>1</p> 	$\Phi = -\frac{1}{4\pi} Ei\left(-\frac{x_{cs}^2}{4at}\right).$ $x_{cs} = r.$ $x_{cs} = rh.$
<p>2</p> 	$\Phi = -\frac{1}{4\pi} \left[ Ei\left(-\frac{x_{cs}^2}{4at}\right) \pm Ei\left(-\frac{x^2 + (z+2L)^2}{4at}\right) \right]$ <p>« »</p> <p>« » -</p> $x_{cs} = r, x = 0, y = 0$
<p>3</p> 	$\Phi = -\frac{1}{4\pi} \left[ +Ei\left(-\frac{r^2}{4at}\right) \mp Ei\left(-\frac{L_1^2}{at}\right) \pm Ei\left(-\frac{L_1^2 + L_2^2}{at}\right) \mp Ei\left(-\frac{L_2^2}{at}\right) \right]$ <p>± Ei</p> <p>:</p> <p>[+ - + -] - x, z - ;</p> <p>[++++] - x, z - ;</p> <p>[++ - -] - x - ; z -</p>
<p>4</p> 	$\Phi = -\frac{1}{4\pi} \left[ Ei\left(-\frac{r^2}{4at}\right) - Ei\left(-\frac{L_1^2}{at}\right) \mp Ei\left(-\frac{L_2^2}{at}\right) \right]$ <p>± Ei</p> <p>:</p> <p>« » -</p> <p>« » -</p>



.3

<p>5</p> 	$= -\frac{1}{4\pi} \sum_{i=1}^{i=n} \delta_i Ei \left( -\frac{x_{hi}^2}{4at} \right),$ $\delta_i = \frac{q_{hi}}{Q}.$ $\Phi = -\frac{1}{4\pi} Ei \left( -\frac{x_{mt}^2}{4at} \right),$ $x_{mt} = \sqrt[n]{x_{h1}x_{h2}\dots x_{hi}}$
<p>6</p> 	$\Phi = \frac{1}{4\pi} \sum_{i=1}^{i=n} \delta_i \left[ Ei \left( -\frac{x_{hi}^2}{4at} \right) \pm Ei \left( -\frac{x_{mhi}^2}{4at} \right) \right]$ $\Phi = \frac{1}{2\pi} \ln \frac{x_{mt,m}}{x_{mt}},$ $x_{mt} = \sqrt[n]{x_{h1}x_{h2}\dots x_{hn}}$ $x_{mt,m} = \sqrt[n]{x_{mh1}x_{mh2}\dots x_{mhn}}$
<p>7</p> 	$\Phi = -\frac{1}{4\pi} \sum_{i=1}^{i=n} \delta_i \left[ +Ei \left( -\frac{x_{hi}^2}{4at} \right) \pm Ei \left( -\frac{x_{mhix}^2}{4at} \right) \pm Ei \left( -\frac{x_{mhz}^2}{4at} \right) \pm Ei \left( -\frac{x_{mho}^2}{4at} \right) \right]$ <p> <math>\pm Ei</math>  <math>:</math>  <math>) [+ - - +] - x, z -</math> ;  <math>) [++++] - x, z -</math> ;  <math>) [+ - + -] - x -</math> ; z -     </p> <p>a) <math>\Phi = \frac{1}{2\pi} \ln \frac{x_{mt,mx}x_{mt,mz}}{x_{mt}x_{mt,o}}</math> ;</p> <p>) <math>\Phi = \frac{1}{2\pi} \ln \frac{x_{mt,mx}x_{mt,mz}}{x_{mt}x_{mt,mz}}</math> ;</p> $x_{mt,mx} = \sqrt[n]{x_{mh1x}x_{mh2x}\dots x_{mhnx}} ;$ $x_{mt,mz} = \sqrt[n]{x_{mh1z}x_{mh2z}\dots x_{mhnz}} ;$ $x_{mt,m0} = \sqrt[n]{x_{mh1,o}x_{mh2,o}\dots x_{mho}} ;$ <p><math>x_{mt} = \dots</math> 6.</p>
<p>-</p>	<p><math>x_h</math></p> <p><math>r_h</math></p>

$u$	$Ei(-u)$	$W(u, v) \quad v$						
		0,05	0,1	0,2	0,6	1,0	2,0	5,0
0	$-\infty$	6,228	4,854	3,505	1,555	0,842	0,228	0,007
0,01	-4,038	4,043	3,815	3,288	1,555	0,841	0,228	0,007
0,02	-3,355	3,326	3,344	2,852	1,553	0,841	0,228	0,007
0,03	-2,959	3,037	2,887	2,690	1,542	0,841	0,228	0,007
0,04	-2,681	2,748	2,629	2,482	1,521	0,841	0,228	0,007
0,06	-2,468	2,458	2,427	2,311	1,493	0,841	0,228	0,007
0,06	-2,295	2,312	2,262	2,167	1,459	0,839	0,228	0,007
0,07	-2,161	2,166	2,123	2,044	1,423	0,836	0,228	0,007
0,08	-2,027	2,021	2,003	1,935	1,386	0,832	0,228	0,007
0,09	-1,919	1,754	1,898	1,839	1,349	0,826	0,228	0,007
0,1	-1,823	1,487	1,805	1,763	1,312	0,819	0,228	0,007
0,2	-1,223	1,221	1,216	1,194	0,996	0,715	0,228	0,007
0,3	-0,906	1,000	0,902	0,890	0,778	0,601	0,216	0,007
0,4	-0,702	0,779	0,700	0,693	0,621	0,502	0,205	0,007
0,5	-0,560	0,559	0,558	0,553	0,504	0,421	0,194	0,007
0,6	-0,454	0,476	0,453	0,450	0,415	0,354	0,177	0,007
0,7	-0,374	0,393	0,373	0,370	0,345	0,300	0,161	0,007
0,8	-0,311	0,310	0,310	0,308	0,289	0,254	0,144	0,007
0,9	-0,260	0,223	0,260	0,258	0,244	0,217	0,128	0,007
1,0	-0,219	0,136	0,219	0,218	0,206	0,186	0,114	0,007
2,0	-0,049	0,049	0,049	0,049	0,047	0,044	0,034	0,005
5,0	-0,001	0,001	0,001	0,001	0,001	0,001	0,001	0,000
8,0	0	0	0	0	0	0	0	0

.11

$$W\left(\frac{at}{x_{cs}^2}; \frac{x_{cs}}{\sqrt{a/b_d}}\right) = \frac{W\left(\frac{at}{x_{cs}^2}; \frac{x_{cs}}{\sqrt{a/b_d}}\right)}{4\pi}; \quad (.8)$$

$$= \frac{W\left(\frac{at}{x_{cs}^2}; \frac{x_{cs}^2}{\sqrt{a/b_d}}\right) \pm W\left(\frac{at}{x_{mcs}^2}; \frac{x_{mcs}}{\sqrt{a/b_d}}\right)}{4\pi}. \quad (.9)$$

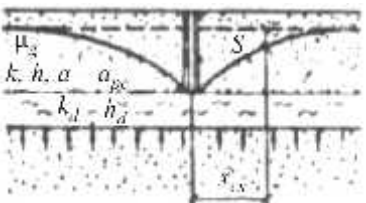
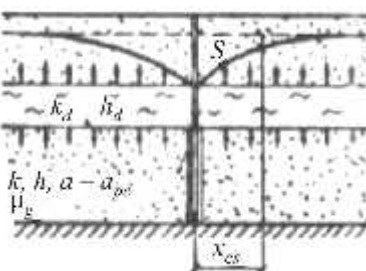
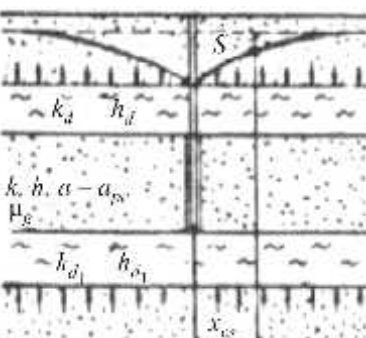
«±» : « » - , « » -  
 $W(u, v)$  .4, :

$$\left. \begin{aligned} u &= \frac{at}{x_{cs}^2} & \frac{at}{x_{mcs}^2}; \\ v &= \frac{x_{cs}}{\sqrt{a/b_d}} & \frac{x_{mcs}}{\sqrt{a/b_d}} \end{aligned} \right\}, \quad (.10)$$

$b_d$

.5.

.5

<p>1</p> 	$b_d = \frac{k_d}{\mu_g h_d}$
<p>2</p> 	$b_d = \frac{k_d}{\mu_e h_d}$
<p>3</p> 	$b_d = \frac{1}{\mu_e} \left( \frac{k_{d1}}{h_{d1}} + \frac{k_{d2}}{h_{d2}} \right)$

$$x_{cs} = r.$$

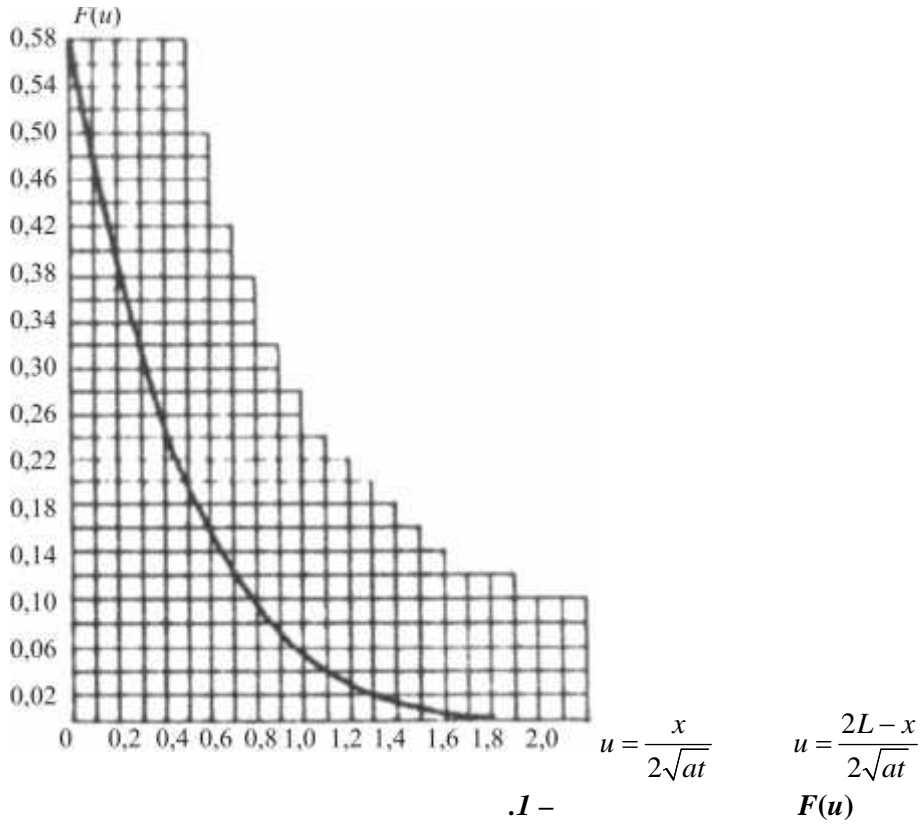
.12

(.1)

$$\Phi = \frac{x_{cs} \left[ F \left( \frac{x_{cs}}{2\sqrt{at}} \right) - F \left( \frac{2L - x_{cs}}{2\sqrt{at}} \right) \right]}{2l \frac{x_{cs}}{2\sqrt{at}}}. \quad (.11)$$

$F(u)$

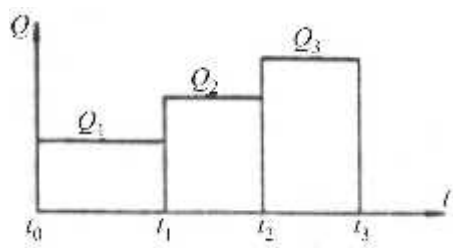
.1.



.13

$Q_i = \text{const}$  ,  $Q(t)$  ,  $i-$  ( .2),  
 $n-$

$$\Phi = \sum_{i=1}^{i=n} \frac{Q_i - Q_{i-1}}{Q_i} \Phi(t - t_{i-1}) \quad ( .12)$$



.2 -

.14

$t,$  .3

.1.

.15

.16

$$q_h \leq 400l_f r_h \sqrt{k} \quad (.13)$$

.17

.18

$$h = \frac{2H - S}{2} \quad (.14)$$

(.1)

$$x_{cs} = r \quad x_{cs} = 0$$

$$S_h = S_l + \frac{q_h}{kh} \Phi_{in} \quad (.15)$$

$$y_h^2 = y_l^2 - \frac{2q_h}{k} \Phi_{in} \quad (.16)$$

$$y_l = H - S_l \quad (.17)$$

$$\Phi_{in} = \Phi_c ; \quad (.18)$$

$$\Phi_c = \frac{1}{2\pi} \ln \frac{s}{2\pi r_h} \quad (.19)$$

-

$$\Phi_{imp} = \Phi_c + \Phi_{com} \quad (.20)$$

$$\Phi_{com} = \frac{h-l_f}{2\pi l_f} \ln \left( \frac{l_f}{r_h} - \varepsilon \right) \quad (.21)$$

.3.

(.21)

yh. .3 bf h  
(.15) (.16)

.19 in imp.

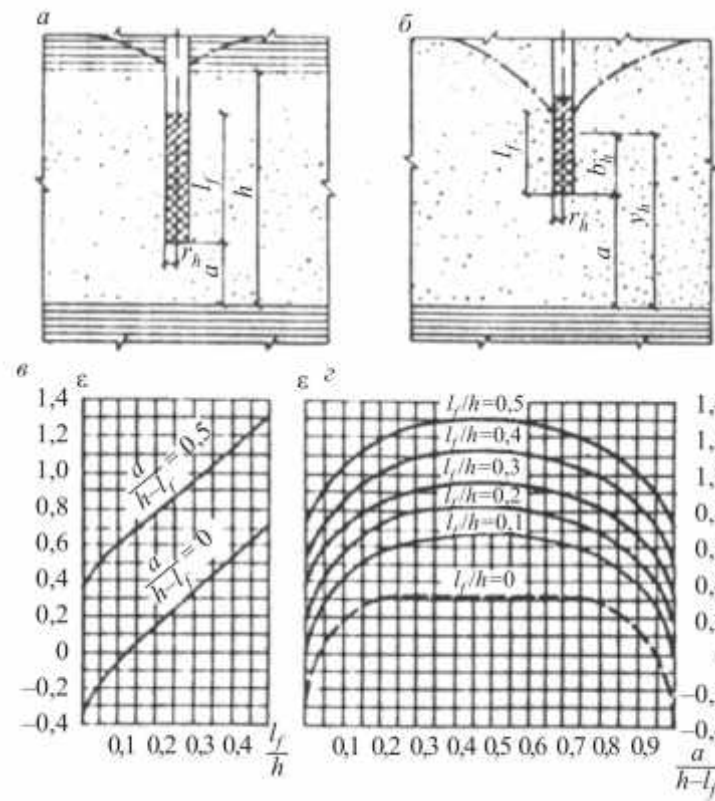
:

$$S = \frac{1}{kh} \sum q_{hi} f_i \quad (.22)$$

.6,

-

$$f_h = 0,159 \ln \frac{r_d}{r_h} \quad (.23)$$



.3 -

(.21) - (.23)

$imp$

$r_{he}$

$$r_{he} = \alpha r_h; \quad \alpha = e^{-2\pi\Phi_{imp}} \quad (.24)$$

(.23)  $r_h$

$r_{he}$

.20

.18

.19

( )

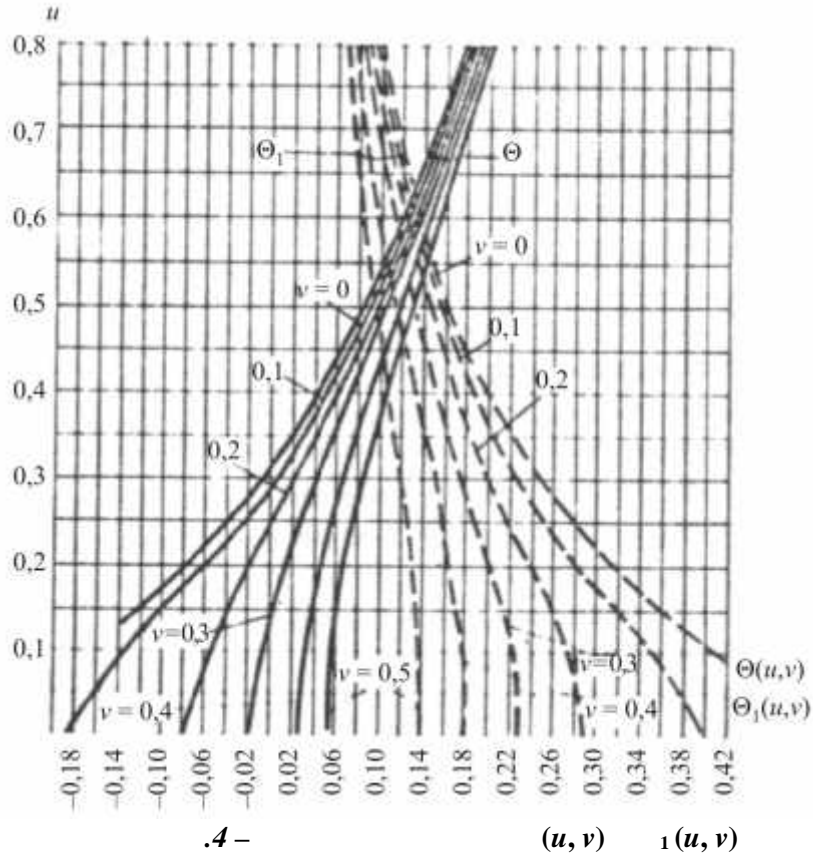
$l_f$  :

$$l_f = \sqrt{\left(1,68 \frac{\sqrt{q_h/k}}{r_h} - 0,51\right) \frac{q_h}{k} + y_h^2}, \quad (.25)$$

(.25)

$y_h,$

$b_f.$



.21

(.1)

3 4

.1.

.18

.22

$$S_l = \left\{ \pi + \frac{2r}{y_l} \left[ \varphi\left(\frac{r}{y_l}; \frac{r_d}{y_l}\right) - \varphi_3\left(\frac{r}{y_l}\right) \right] \right\} = S_{cs} \left[ \ln \frac{8r}{r_h} + \frac{2r}{y_l} \varphi\left(\frac{r}{y_l}; \frac{r_d}{y_l}\right) \right]. \quad (.26)$$

3

.1  $y_l = h;$

4

$l = -S_i;$

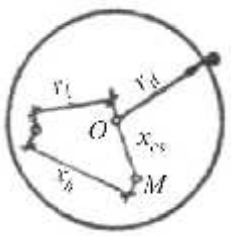
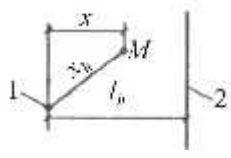
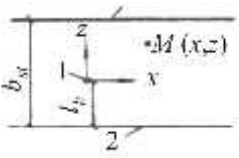
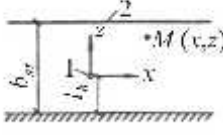


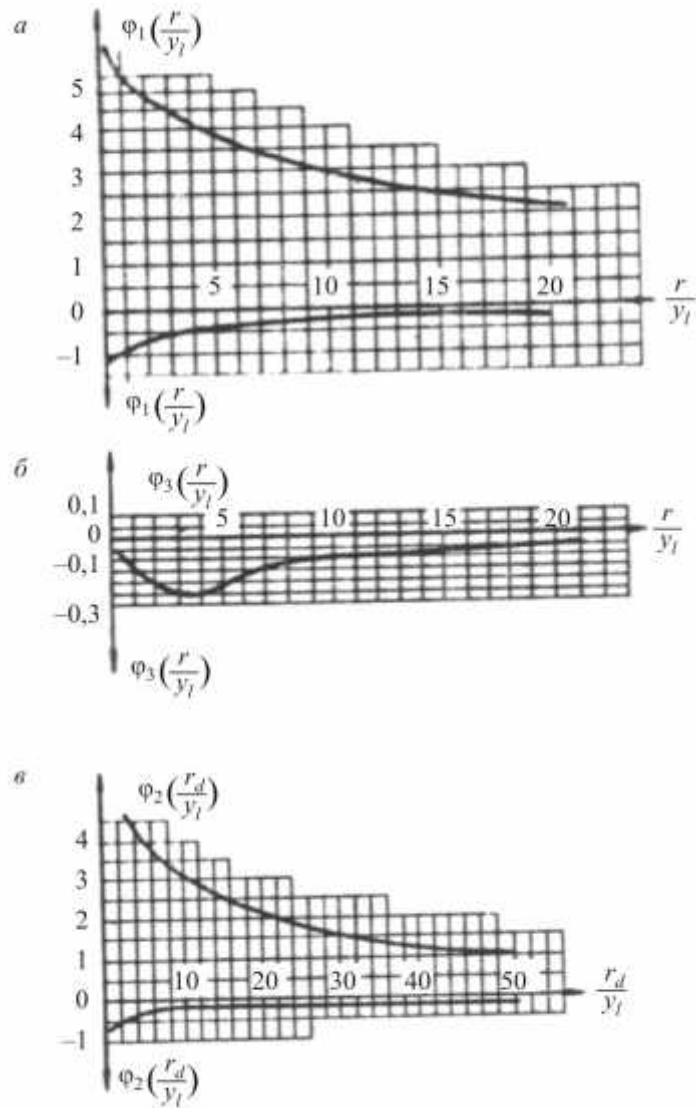
$$\Phi\left(\frac{r}{y_l}; \frac{r_d}{y_l}\right) = \Phi_1\left(\frac{r}{y_l}\right) - \Phi_2\left(\frac{r_d}{y_l}\right). \quad (.27)$$

$$\Phi_1\left(\frac{r}{y_l}\right); \Phi_2\left(\frac{r_d}{y_l}\right) \quad \Phi_3\left(\frac{r}{y_l}\right)$$

.5.  
(27)

.6

<p>1</p> 	$f = 0,159 \ln \frac{\sqrt{r_d + \frac{x_{cs}^2 x_h^2}{r_d^2} - x_{cs}^2 - r_i + x_h^2}}{x_h}$
<p>2</p>  <p>( I - ; 2 -</p>	$f = 0,159 \ln \frac{\sqrt{4l_h^2 - 4l_h x + x^2}}{x_h}$ <p>x</p>
<p>3</p>  <p>I - ; 2 -</p>	$f = \Theta\left(\frac{x}{b_{st}}; \frac{2l_h + z}{b_{st}}\right) - \Theta\left(\frac{x}{b_{st}}; \frac{z}{b_{st}}\right)$ $u = \frac{x}{b_{st}}; \quad v = \frac{z}{b_{st}} \quad v = \frac{2l_h - z}{b_{st}}$ <p>(u, v) .4</p>
<p>4</p>  <p>I - ; 2 -</p>	$f = \Theta_1\left(\frac{x}{b_{st}}; \frac{l_h + z}{b_{st}}\right) + \Theta_1\left(\frac{x}{b_{st}}; \frac{z}{b_{st}}\right)$ $u = \frac{x}{b_{st}}; \quad v = \frac{l_h + z}{b_{st}} \quad v = \frac{l_h - z}{b_{st}}$ <p>1(u, v) .4</p>



$-\varphi_1(u); -\varphi_2(u); -\varphi_3(u)$

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(.1)

5 6

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(.11).

.24

(.1)

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.4

18-25 %, -  
30-60 %.

$d_{i,mi}$

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$20 / ^3(2 / ^3)$

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2-10

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6	,	-
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0,003.

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 ),<sup>3/</sup> ;

$Ei(-u)$  — ;  
 $F(u)$  — ( ;  
 )

$H$  —  
 $H_s$  — ( ), ;

, ;  
 $I$  — ;  
 $I_{cr}$  — ;  
 $L$  — ( )

, ;  
 $Q$  —

,<sup>3/</sup> ;  
 $S$  — , ;  
 $S_{cs}$  — , ;

, ;  
 $S_h$  — , ;  
 $S_l$  — ( )

, ;  
 $W(u, \epsilon)$  —

;  
 — , ,  
 , — : ,<sup>2/</sup> ,<sup>2/</sup> ;  
 $a_{lc}$  — ,<sup>2/</sup> ;

— , ;  
 $b$  — ( ), ;  
 $b_d$  — , , / ( <sup>-1</sup>);  
 $b_f$  — , ;  
 $b_{st}$  — ( ) , ;

$d_{inf}$  — , 10 %  
 , ;

$d_{fil}$  – ;  
 $d_{d,mt}$  – 50 % ;  
 $d_h$  – ;  
 $d_k$  – ;  
 $d_{mt}$  – 60 % ;  
 $d_{1,mt}, d_{2,mt}, d_{3,mt}$  – 60 % ;  
 1-, 2- 3- ;  
 $d_{sup}$  – 80 % ;  
 $e$  – ;  
 $f$  – ;  
 $f_h$  – ;  
 $f_i$  – ;  
 $h$  –  $(2H-S)/2$  ;  
 $h_d$  – ;  
 $h_{in}$  – ;  
 $i$  – ;  
 $k$  – , / ;  
 $k_d$  – , / ;  
 $k_s$  – , / ;  
 $l$  – ;  
 $l_c$  – ;  
 $l_f$  – ;  
 $l_h$  – ;  
 $n$  – ;  
 $p$  – , / ;  
 $q$  –  $( \quad 1$   
 $\quad )^{2/}$  ;

$Q_h$  — ,  $3/$  ;  
 $Q_{hi}$  —  $i-$  ,  $3/$  ;  
 $Q_{in}$  — ,  $3/$  .  
 $r$  — , ;  
 $r_d$  — , ;  
 $r_h$  — ( , ), ;  
 $r_{he}$  — , , ;  
 $r_{in}$  — , ;  
 $r_s$  — , ;  
 $s$  — ( , ;  
 ), ;  
 $t$  — ( , ;  
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 $t_{fm}$  — - , ;  
 $t_s$  — , ;  
 $(u, v)$  — ;  
 $v$  — / ;  
 $, , z$  — ;  
 $x_{cs}$  — ( )  
 , ;  
 $x_{mcs}$  — , ;  
 $x_{hi}$  —  $i-$  (  $i-$  ) , ;  
 $x_{mhi}$  —  $i-$  , ;  
 $x_{mhix}$  —  $i-$  , ;  
 $x_{mhiz}$  —  $i-$  , ;  
 $x_{mhio}$  —  $i-$  , ;  
 $x_{mt}$  — , ;  
 $x_{mt,m}$  — , ;  
 $x_{mt,mx}$  — , ;  
 $x_{mt,mz}$  — , ;  
 $x_{mt,mo}$  —  $z,$  ;  
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		,	;	
<i>cs</i>	—	(		)
		,	;	
<i>y<sub>h</sub></i>	—	(		)
<i>y<sub>l</sub></i>	—	(		)
		,	;	
	—			
			;	
<i>in</i>	—			
			;	
<i>c</i>	—			
			;	
<i>com</i>	—			
		—		
		;		
<i>imp</i>	—			
			;	
$Q(u,v), Q_1(u,v)$	—			
			;	
	—			
		,		
			;	
	—			
		;		
$\beta$	—			
$\delta_i$	—			
		;		
	—			
		—		
		;		
$\mu_g$	—			
$\mu_e$	—			
$\varphi(u,v), \varphi_1(u), \varphi_2(v), \varphi_3(u)$	—			
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